

Project Title

Intelligent Management of Automated Guided Vehicles (AGVs) for ad-hoc Surgical Instrument Conveyance

Project Lead and Members

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Organisation(s) Involved

SingHealth, National University of Singapore, Singapore General Hospital

Healthcare Family Group(s) Involved in this Project

Healthcare Administration

Applicable Specialty or Discipline

Operating Theatre, Facilities Engineering

Aim(s)

The objective of this project is to find the optimal AGV docking location and optimal scenario: number of AGVs and AGV restocking frequency based on three criterias:

- 1) AGVs utilisation rate*
- How often AGVs are used to serve the ad-hoc requests
- 2) Cost per AGV fulfilment*
- Total cost of AGVs / Total number of ad-hoc request fulflled by AGVs
- 3) Breakeven period*

Time taken for the monetary benefits from AGVs to surpass the cost of AGVs

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Background

See poster appended/ below

Methods

See poster appended/ below

Results

See poster appended/ below

Conclusion

See poster appended/ below

Additional Information

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Project Category

Care & Process Redesign

Value Based Care, Productivity, Manhour Saving, Operational Managmeent

Keywords

Automated Guided Vehicles

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Intelligent Management of Automated Guided Vehicles (AGVs) for ad-hoc Surgical Instrument Conveyance

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Background & Introduction

Operating Theatre (OT) Circulating Nurses are highly trained manpower that is critical part of surgical teams. However, they can spend up to 20% of their time searching and fetching sterile surgical instruments from and around the OTs.

Aim

The objective of this project is to find the optimal AGV docking location

These highly trained and specialized nurses may have their manpower wasted on these repetitive manual tasks and a solution is needed to reduce the inefficiency. The use of Automated Guided Vehicles (AGV) is recommended in reducing this manpower wastage.

Workflow

and optimal scenario: number of AGVs and AGV restocking frequency based on three criterias:

1) AGVs utilisation rate*

How often AGVs are used to serve the ad-hoc requests

2) Cost per AGV fulfilment*

Total cost of AGVs / Total number of ad-hoc request fulfilled by AGVs

3) Breakeven period*

Time taken for the monetary benefits from AGVs to surpass the cost of AGVs

Methodology

Model Output Analysis (Part Model Output Analysis Simulation Model (Part2: Optimal docking 1: Optimal restocking Construction frequency & No. of AGVs) location) Obtain utilization rate of AGV in Analyse <u>average travelling time</u> Gathering Data fulfilling requests for 40 over of AGV scenarios. Model Construction (Logic & Docking locations: Top right, Three Criteria to determine Path Mover System that bottom right, top left, bottom optimal solution: simulates actual layout) <u>left</u> 1. At least 90% AGV utilization

- Step 1: Using relevant data such as OT layout and frequencies for each adhoc instrument type requested by each theatre, the simulation model was constructed. The number of yearly ad-hoc request is estimated to be 23,003 requests (assuming that daily request frequency follows normal distribution with mean and standard deviation of 36 and 5 minutes)
- Step 2: The developed model deployed to simulate 40 different scenarios (2-5 no. of AGVs & 1-10 times per day restocking frequency) and obtained AGV utilisation rate for each case. Lifecycle cost analysis of AGVs was carried out to compute the cost per AGV fulfilment and AGVs cost breakeven period as well.



- Step 3: The optimal solution was found based on the three criteria 1) At least 90% AGV utilisation rate.
 - 2) Lowest cost per AGV fulfilment.
 - 3) Shortest breakeven period.
- Step 4: Using the best scenario, the model was fitted with four different docking locations (Top right, bottom right, top left, bottom left). The optimal location is identified by shortest average travelling time of AGVs.

Results

		ſ	Number of	Number of				Cost of	
	Number of	f	ulfilled by	fulfilled by			Utilisation	fulfilled by	Breakeven
Frequency	AGVs	-	AGV	Nurse	(Cost of AGV	Rate	AGV	Period
10)	4	23003		0	135568	100.00%	5.89	3.64
ç)	5	23003		0	169460	100.00%	7.37	4.55
10)	5	23003		0	169460	100.00%	7.37	4.56
8	3	5	22991		12	169460	99.95%	7.37	4.54
ç)	4	22991		12	135568	99.95%	5.90	3.64
6	6	5	22979		24	169460	99.90%	7.37	4.53
8	3	4	22967		36	135568	99.84%	5.90	3.64
7	7	5	22967		36	169460	99.84%	7.38	4.54
5	5	5	22943		60	169460	99.74%	7.39	4.52
7		4	22930		73	135568	99.68%	5.91	3.63
10)	3	22919		84	101676	99.63%	4.44	2.74
6	5	4	22870	1	.33	135568	99.42%	5.93	3.64
9		3	22835	1	.68	101676	99.27%	4.45	2.75
4	ļ.	5	22751	2	52	169460	98.90%	7.45	4.55
8	3	3	22679	3	24	101676	98.59%	4.48	2.76
5	5	4	22585	4	18	135568	98.18%	6.00	3.68
7	7	3	22357	6	46	101676	97.19%	4.55	2.8
3	3	5	22093	9	10	169460	96.04%	7.67	4.68
4	1	4	21996	10	07	135568	95.62%	6.16	3.77
6	5	3	21977	10	26	101676	95.54%	4.63	2.84
10)	2	21648	13	55	67784	94.11%	3.13	1.94
9)	2	21168	18	35	67784	92.02%	3.20	1.98
5	5	3	21090	19	13	101676	91.68%	4.82	2.95

The scenario of 2 AGVs & 10 times per day restocking frequency (highlighted in yellow) is the optimal solution. It has the utilisation rate of 94.1%, the lowest cost per AGV fulfilment and shortest breakeven period.

For docking location, the optimal location is top right which is also the current location.



Conclusion

With the simulation model, different scenarios were considered to find optimal solution. Using the three criteria, the optimal number of AGVs and restocking frequency is 2 and 10 times per day respectively. The optimal docking location should be at the top right of the OT floor plan.

The relationship of AGV utilization rate against restocking frequency and number of AGVs can be described by the following equation: Utilisation Rate = $10.88 + 58.16 \lg(AGV) + 64.28 \lg(freq)$, which can give a prediction of adjusted AGV number or restocking frequency if in future there is any change in AGV or manpower arrangement.